



## Attitude and Heading Reference System

### AHRS-S305

#### **Description:**

The AHRS-S305 is Watson Industries' newest Attitude and Heading Reference System. Standard for an attitude gyro system, the AHRS-S305 has a sensor package that consists of three solid state angular rate gyros, three accelerometers, and a triaxial fluxgate magnetometer used as a heading reference. This AHRS differs from our other inertial gyro packages because this sensor uses smaller MEMS gyros. This makes the AHRS-S305 more economical and half the size of the AHRS-E304 which uses VSG gyros for enhanced accuracy and signal stability.



The signals from three solid state angular rate gyros are coordinate transformed and then integrated to produce attitude and heading outputs that reflect normal attitude coordinates. These attitude and heading signals are compared to the accelerometers and the fluxgate magnetometer to derive gyro drift error. These errors are filtered over a long time constant and are used to adjust system biases so that the long-term convergence of the system is to the vertical references and the magnetic heading. A velocity input can be used to improve the overall stability and accuracy of the system by calculating centrifugal forces and velocity changes on the vertical reference and compensating for them.

This is a microprocessor-based system using a 16 bit A/D converter, a 12 bit D/A converter and an RS-232 interface. The analog attitude and heading outputs are updated 71.11 times per second. The serial interface is highly configurable and provides access to almost all operational parameters.

- Solid State, Strapdown System
- Small Size
- Low Cost, Low Power
- Rugged, High Reliability
- Analog and RS-232 Serial Outputs
- PC Heading Calibration
- One Year Limited Warranty
- Engineering Support

#### **Applications:**

The AHRS-S305 is useful for land and sea applications. Some examples include control and stabilization of remote piloted subs or antennas, robotics research, and road surface measurement.



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## AHRS-S305 Specifications

### Attitude

|                      |       |                      |
|----------------------|-------|----------------------|
| Range: Bank          | ±180° |                      |
| Range: Elevation     | ±90°  |                      |
| Resolution:          | 0.02° | Binary mode (14 bit) |
| Analog Scale Factor: | 18°/V | ±10V Output          |
| Accuracy: Static     | ±0.5° |                      |
| * Accuracy: Dynamic  | ±2%   |                      |

### Heading

|                      |           |                      |
|----------------------|-----------|----------------------|
| Range:               | 0° - 360° |                      |
| Resolution:          | 0.02°     | Binary mode (14 bit) |
| Analog Scale Factor: | 18°/V     | ±10V Output          |
| † Accuracy: Static   | ±1°       |                      |
| * Accuracy: Dynamic  | ±2%       |                      |

### Angular Rate

|                         |             |                      |
|-------------------------|-------------|----------------------|
| Range: Roll, Pitch, Yaw | ±100°/sec   |                      |
| Resolution:             | 0.01°/sec   | Binary mode (14 bit) |
| Analog Scale Factor:    | 10°/sec/V   | ±10V Output          |
| Scale Factor Accuracy:  | 2%          |                      |
| Bias: Roll, Pitch, Yaw  | < ±0.3°/sec |                      |
| Non-Linearity           | < 0.05%     | Full scale range     |
| Bandwidth               | 20 Hz       |                      |

### Acceleration

|                        |        |                  |
|------------------------|--------|------------------|
| Range: X, Y, Z         | ±10g   |                  |
| Resolution:            | 4mg    |                  |
| Scale Factor Accuracy: | 1%     |                  |
| Bias: X, Y, Z          | < ±5mg |                  |
| Non-Linearity:         | < 1%   | Full scale range |
| Bandwidth:             | 20 Hz  |                  |

### Magnetic

|                        |              |                      |
|------------------------|--------------|----------------------|
| Range: X, Y, Z         | ±1000 mGauss |                      |
| Resolution:            | 0.1 mGauss   | Binary mode (14 bit) |
| Scale Factor Accuracy: | 1%           |                      |
| Bias: X, Y, Z          | < ±5mGauss   |                      |
| Non-Linearity:         | < 0.01%      | Full scale range     |
| Bandwidth:             | 10 Hz        |                      |

### Environmental

|                        |                |                  |
|------------------------|----------------|------------------|
| Temperature: Operating | -40°C to +85°C |                  |
| Temperature: Storage   | -55°C to +85°C |                  |
| Vibration: Operating   | 2.5g rms       | 20 Hz to 2 kHz   |
| Vibration: Survival    | 10g rms        | 20 Hz to 2 kHz   |
| Shock: Survival        | 500g           | 10ms ½ sine wave |

### Electrical

|                                 |               |                      |
|---------------------------------|---------------|----------------------|
| Frame Rate                      | 71.1 Hz       | Maximum              |
| Startup Time: Data              | 5 sec         |                      |
| Startup Time: Fully operational | 10 sec        |                      |
| Input Power:                    | 10 to 30VDC   | 2.8W                 |
| Input Current:                  | 215mA @ 12VDC | 115mA @ 24VDC        |
| Input Velocity: (Optional)      | ±10VDC        | Full scale (±800kph) |
| Digital Output                  | RS-232        |                      |
| Analog Output                   | ±10VDC        |                      |
| Analog Output Impedance:        | 300 Ohm       | Per line             |

### Physical

|                                  |                              |                     |
|----------------------------------|------------------------------|---------------------|
| Axis Alignment:                  | < 0.25°                      |                     |
| Size: Including Mounting Flanges | 3.24"W x 5.78"L x 2.38"H     | 8.2 x 14.7 x 6 (cm) |
| Weight:                          | 22oz (1.4lb)                 | 620g (0.6kg)        |
| Connection:                      | 25 pin male "D" subminiature |                     |

\* Assumes accurate velocity data.

Actual accuracy can be calculated as the listed percentage multiplied by the change in value over the entire dynamic maneuver.

† Static heading accuracy is dependent on the magnetic environment.

This sensor will meet or exceed this spec within the 48 contiguous United States.

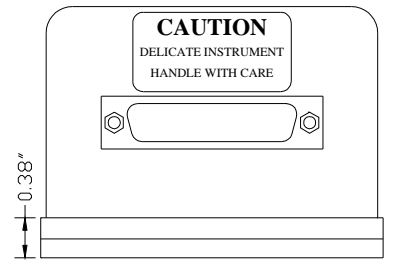
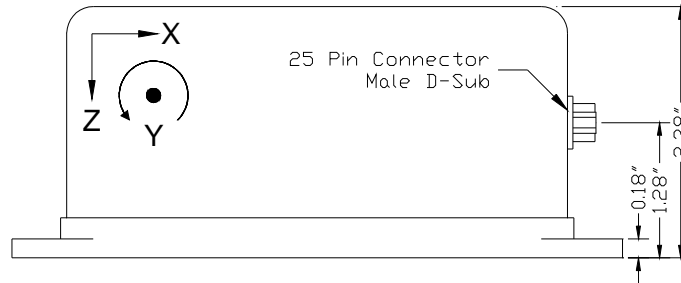
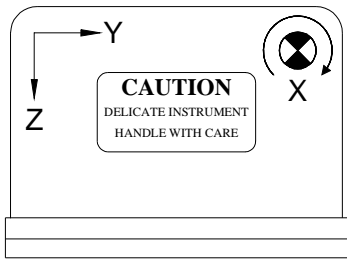
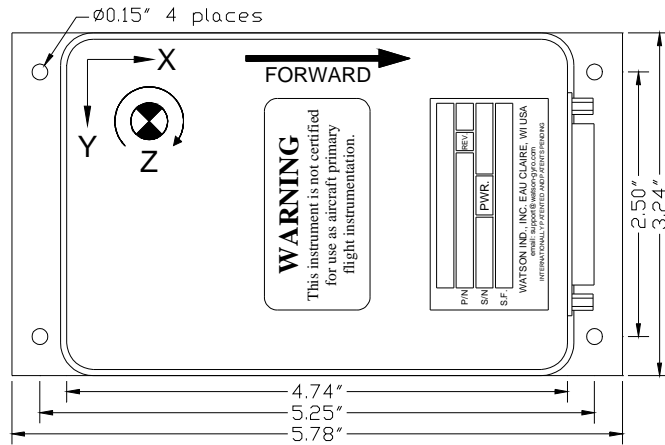
- Specifications are subject to change without notice.
- This product may be subject to export restrictions. Please consult the factory.



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**Dimensions:**



03/10 DAO



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